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Use of UAS in Bridge Inspection

Christopher Parrish Oregon State University



FHWA – EDC-5

Outline

- Projects conducted to date
- Motivation for use of UAS in bridge inspection
- Operations
 - » Aircraft and sensor selection
 - » Workflow
 - » Safety plan
- Results of bridge inspections
- Cost-benefit analysis
- Key findings



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Projects

OSU UAS Bridge Inspection Projects:

- » PacTrans (2015): Cost-Effective Bridge Safety Inspection using Unmanned Aerial Vehicles
- » Oregon DOT (2015-2018): SPR 787 Eyes in the Sky: Bridge Inspections with Unmanned Aerial Vehicles

Related projects

- » FHWA (2015-2017): Effective Use of Geospatial Tools in Highway Construction (with WSP)
- » PacTrans (2018): UAS in Transportation Expo
- » PacTrans (2017-2019): An Airborne Lidar Scanning and Deep Learning System for Real-time Event Extraction and Control Policies in Urban Transportation Networks
- » PacTrans (2020): Unmanned Aircraft Systems in Transportation: Research-to-Operation (R2O) Peer Exchange



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Motivation

UAS

- » Simply one tool--but a potentially powerful one--for bridge inspection
 - Provides new method of remotely viewing bridge elements at high-resolution, while keeping both feet on the ground
 - Can reduce lane closures, use of bucket trucks, and climbing for some percentage of bridges to be inspected annually
 - Enhance safety and reduce costs for some percentage of inspections





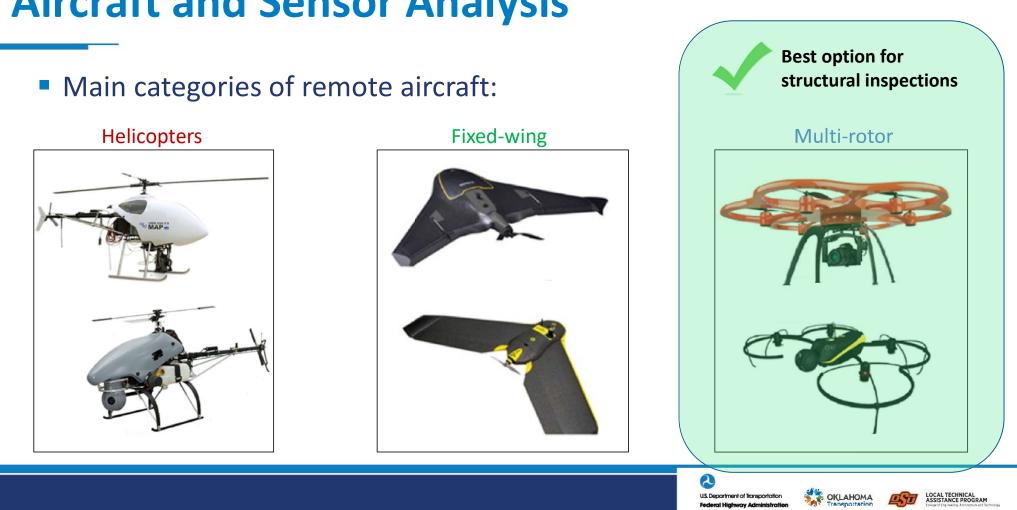
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Specific Project Goals (SPR 787)

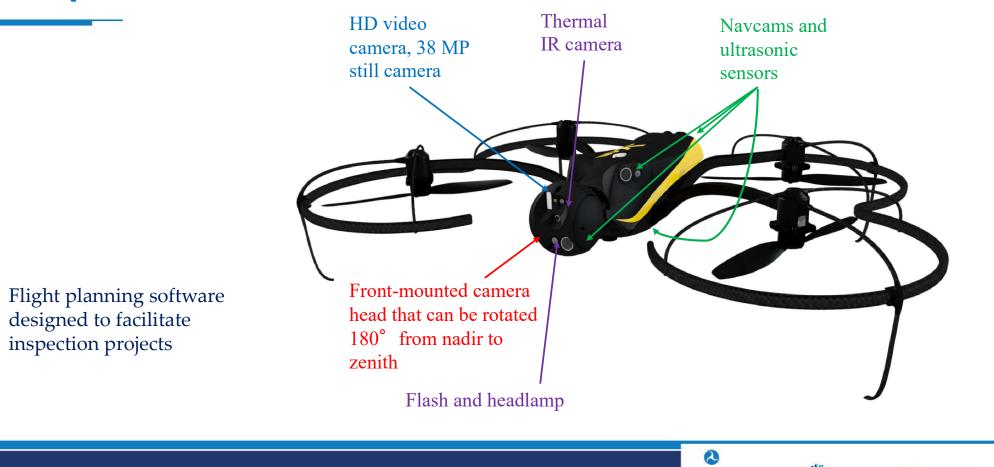
- Evaluate performance of UAS for bridge inspection
- Identify inspection requirements that can and cannot be satisfied with UAS
- Provide cost-benefit analysis
- Develop SOPs
- Develop safety plan
- (Also extend analysis to inspection of communication towers)





Aircraft and Sensor Analysis

Components of a UAS Designed for Structural Inspections



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Importance of Rotating Sensor Head

A) Camera optical axis pointing down (nadir)

» Typical mapping configuration

B) Camera optical axis pointing horizontal

» Common in inspection work

C) Camera optical axis tilted up

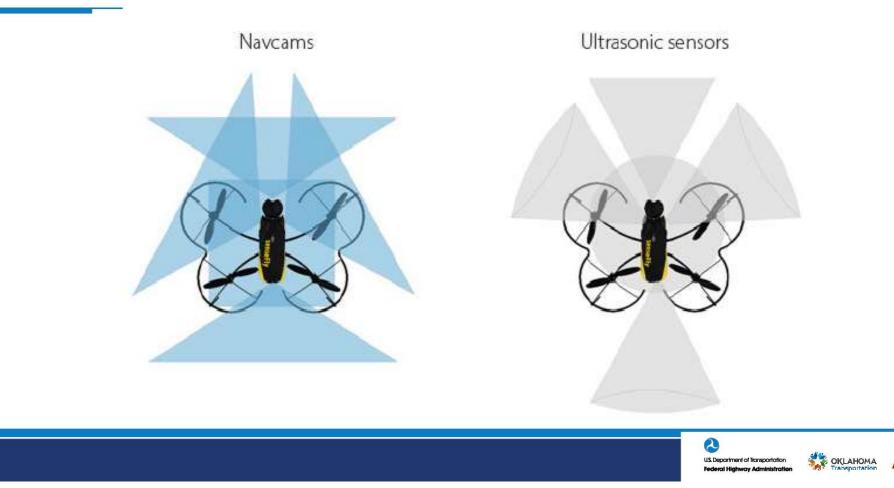
» Common in inspection work





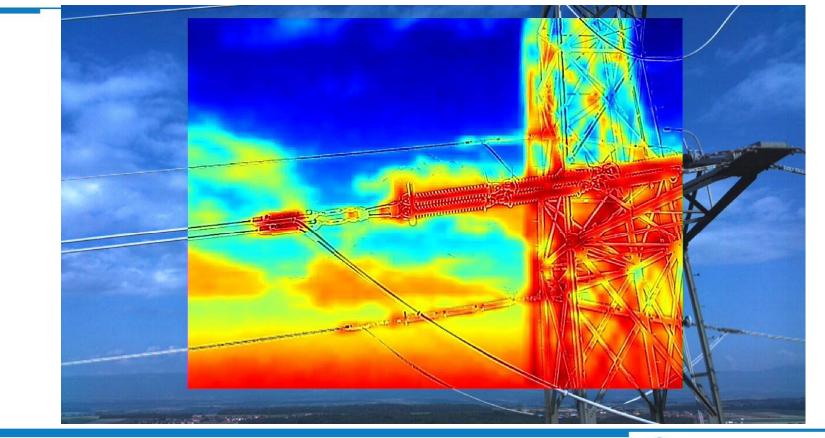


Importance of NavCams & Obstacle Avoidance



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Thermal Camera



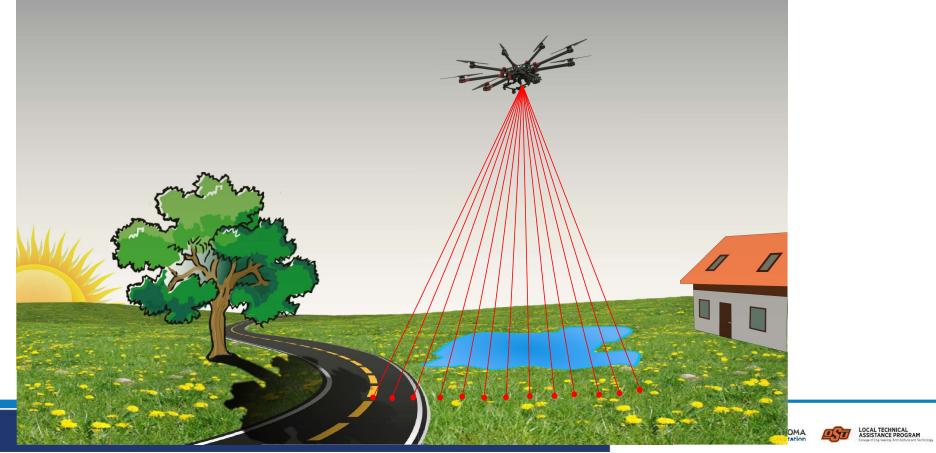


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Sensor Types: Lidar

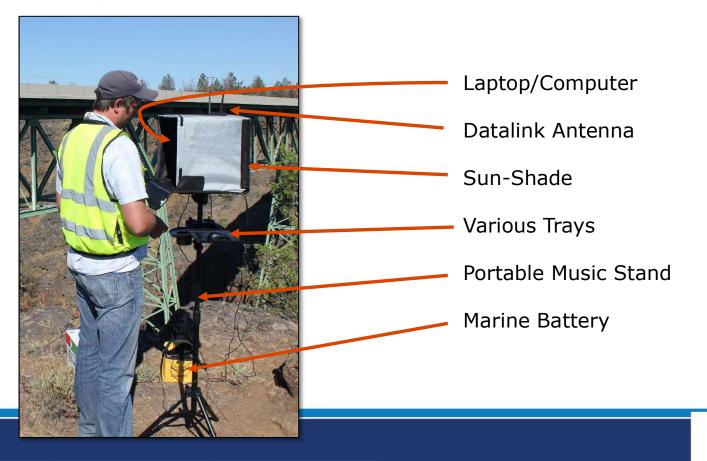




Sensor Types: Cameras



Ground Control Station



Takeoff and landing zone

- » Large, clear, flat area
- » Away from people
- » Access permissions (!)

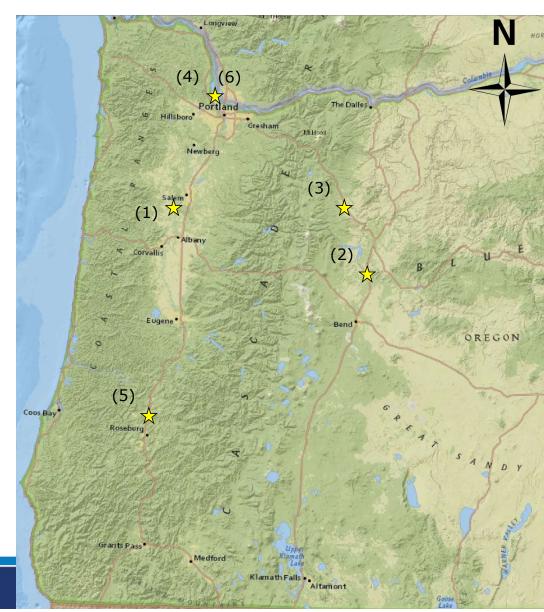


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Test Bridge Inspections

- (1) Independence Bridge
- (2) Crooked River Bridge
- (3) Mill Creek Bridge
- (4) St. Johns Bridge
 - » Preliminary
- (5) Winchester Bridge
- (6) St. Johns Bridge
 - » Detailed



Test Bridge Inspection: Independence Bridge, Sept 2015

- Location: Independence, OR
- Airframe: Phantom 3 Pro
- Flight objective
 - » Test bridge inspection workflow» Capture still and video imagery

Details

- » Large deck plate girder bridge
 - 675.4 m long
 - Longest span: 46.3 m
- » Classified as Fracture Critical







Independence Bridge: Imagery Examples







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Independence Bridge: Imagery Examples







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Test Bridge Inspection: Crooked River Bridge, July 2016

- Location: 8 km north of Terrebonne, OR
- Airframe: senseFly Albris
- Flight objective
 - » Capture high-quality imagery for inspection purposes
 - » Targeting specific areas that are difficult to inspect using traditional methods
 - » Create 3D model via SfM

Details

- » Steel Arch Bridge
- » 141 m long
 - Longest span: 100 m
- » Pedestrian only

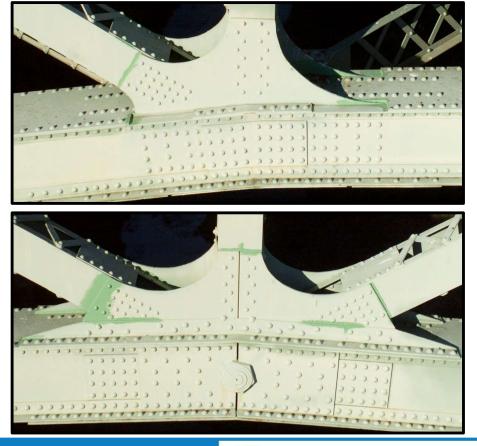






Crooked River Bridge: Imagery Examples



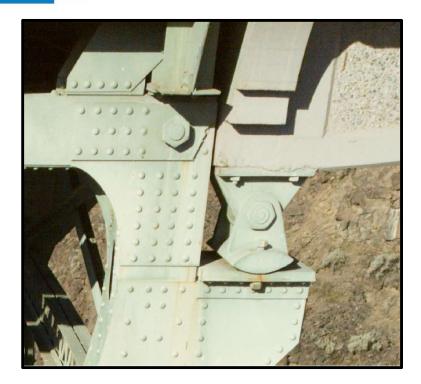


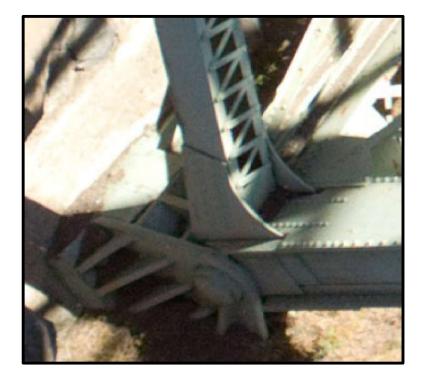


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Crooked River Bridge: Imagery Examples











Crooked River Bridge: Mapping Flights

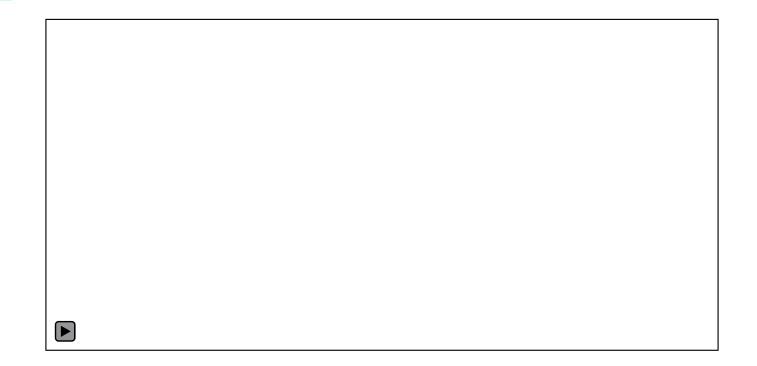








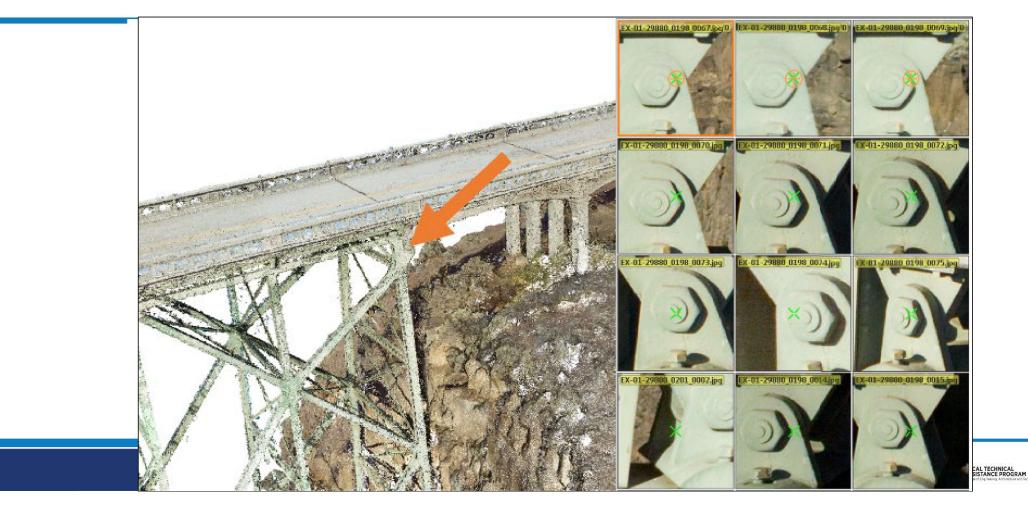
Crooked River Bridge: Point Cloud







Point Cloud ↔ Raw Imagery



Test Bridge Inspection: Mill Creek Bridge, July 2016

- Location: 17 km NW of Warm Springs, OR
- Airframe: senseFly Albris
- Flight objective
 - » Capture high-quality imagery for inspection purposes
 - Targeting specific areas that are difficult to inspect using traditional methods

Details

- » Cantilevered Warren deck truss bridge
- » 163 m long
 - Longest span: 50 m

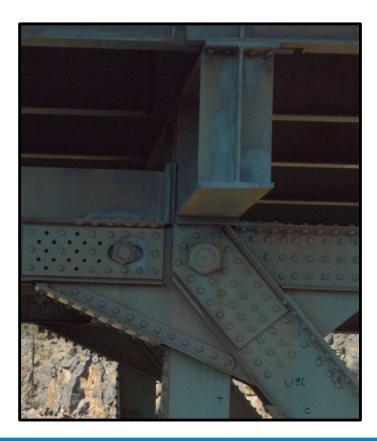




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Mill Creek Bridge: Imagery Examples





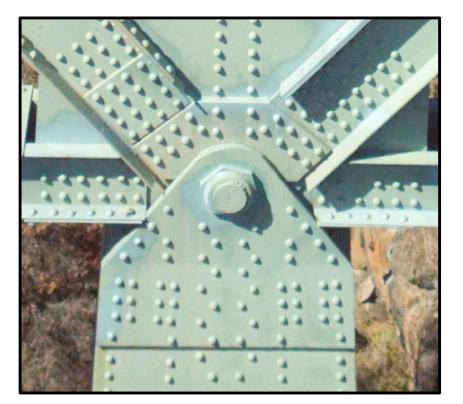


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Mill Creek Bridge: Imagery Examples









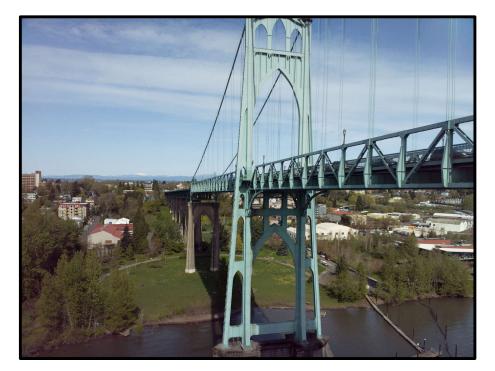


Test Bridge Inspection: St. Johns Bridge (Prelim Test), Sept 2016

- Location: Portland, OR
- Airframes: senseFly Albris, s900 with Sony WX500 (30x optical zoom)
- Flight objective
 - » Test of optical zoom camera
 - » Capture high-quality imagery

Details

- » Metal Riveted Warren deck truss
- » Wire Cable Suspension
- » 1100 m long
 - Longest span: 368 m





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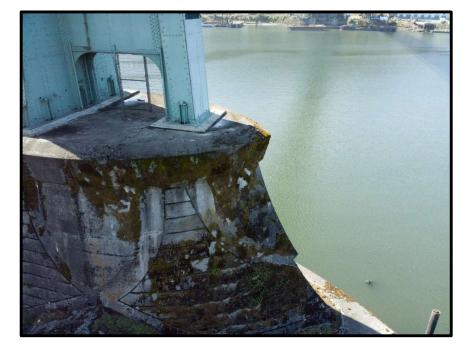




















Test Bridge Inspection: Winchester Bridge, March 2017

- Location: Winchester, OR
- Airframes: senseFly Albris
- Flight objective
 - » Capture imagery while receiving real-time input from inspectors

Details

- » Warren deck truss bridge
- » Southbound bridge of I-5
- » 500 m long
 - Longest span: 42 m





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Winchester Bridge: Imagery Examples











Winchester Bridge: Imagery Examples









Test Bridge Inspection: St. Johns Bridge (Detailed Test), April 2017

- Location: Portland, OR
- Airframes: senseFly Albris
- Flight objective
 - » Week-long, in-depth inspection
 - » Test inspecting directly under deck

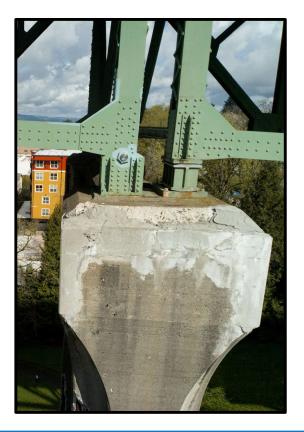
Details

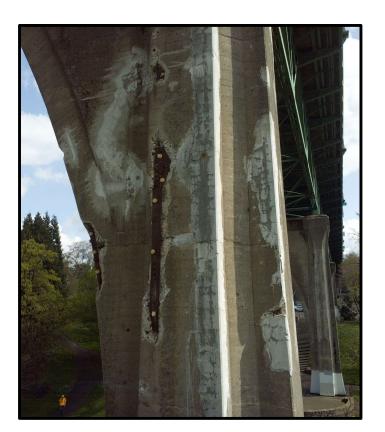
- » Metal Riveted Warren deck truss
- » Wire Cable Suspension
- » 1100 m long
 - Longest span: 368 m
- » Flight limited to eastern 550 m from center of main span













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Cost-Benefit Analysis Procedures

1. Establish baseline costs for bridge inspections conducted *without* the use of UAS by compiling existing data from Oregon DOT

» 33 bridge inspection project budget spreadsheets

2. Determine the percentage of bridges that Oregon DOT inspects that are suitable for UAS inspection

» Airspace, proximity to populated areas, vegetation, size of bridge, etc.

- 3. Establish which project cost categories could be reduced (not eliminated) through use of UAS:
 - » Personnel time (field and office)
 - » Equipment rental/usage (e.g., snooper trucks)
 - » Traffic control
 - » Travel (including lodging, meals and incidentals)





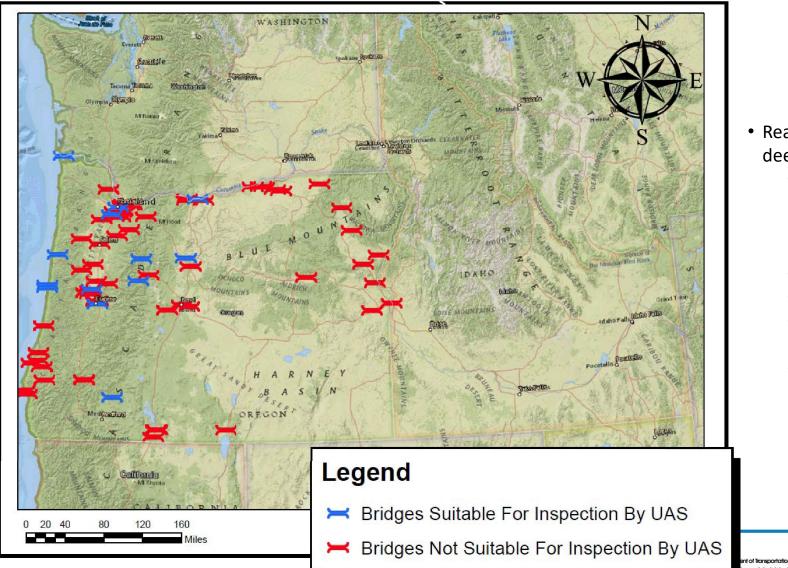
Cost-Benefit Analysis Procedures (cont'd)

- Estimated annual cost savings = (average cost savings per suitable bridge) × (# of bridges/yr inspected by ODOT) × (percentage of bridges suitable for UAS inspection)
- 5. Estimate costs:
 - » Cost of purchasing 3 UAS
 - » Annual maintenance cost
 - » Data storage

 $B = \$10,200(730 \times 0.16) = \$1,191,360$ $\sum C = \$117,237 + \$4,500 + \$5,700 = \$127,437$

$$BCR = \frac{\$1,191,360}{\$127,437} \approx 9$$





- Reasons bridges were deemed "not suitable"
 - Low height, low clearance bridges, where it wouldn't be worthwhile to use UAS
 - Airspace
 - Access issues
 - Vegetation poses risks to UAS

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• Lack of suitable takeoff/landing site

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Key Project Findings

- UAS can assist to varying degrees in many required elements of a bridge inspection
 - » Very well suited for **initial and routine inspections** and for satisfying report requirements related to geometry and structural evaluation
- Cracks, pack rust, connections, hardware and bearing locations were all determined to be readily-identifiable in the imagery collected in this project, with the recommended flight procedures
- Cost-benefit analysis provides strong indication of positive ROI for implementing UAS in ODOT's bridge inspection program
 - » Potential for >\$1M in savings/year from use of UAS in structural inspections in large bridge inspection program

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» Should be refined as more data becomes available

Practical Recommendations/Lessons-Learned

Remote aircraft requirements

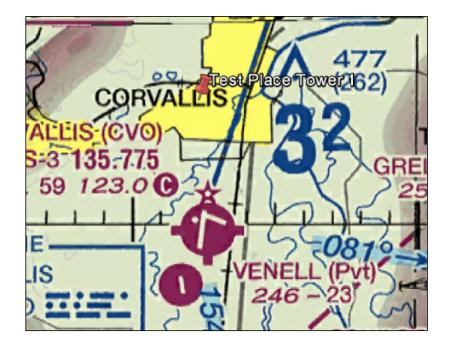
- » Variable tilt (0-180°) camera
- » Zoom lens
- » Obstacle avoidance capabilities
- » Establish max wind speeds for structural inspections (aircraft dependent)

Personnel requirements

- » UAS bridge inspection flight crews should have at least a basic level of expertise in photography
 - ISO, aperture, shutter speed
- » Frequent practice (proficiency flights) specifically for structural inspection
 - Simulate: loss of GPS, wind gusts, operating near large structure



Safety Plan



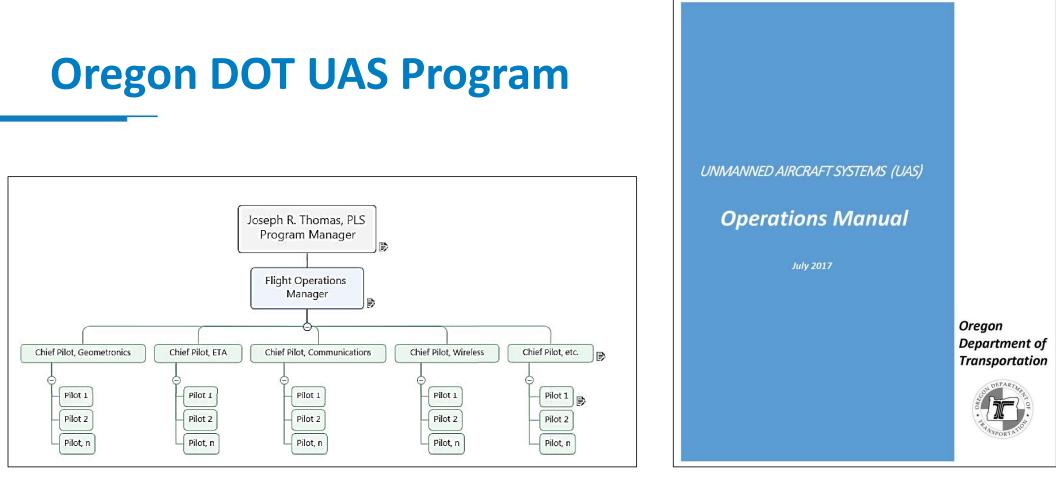
Date of Assessment:			04/25/2016 Perso			ersonnel:	Pilot in Command:		Tom Normandy	
Structure Type:			Communication Tower				Primary Observer:		Matt Gillins	
Location of			44°26'10.8" N 122°59'07.1" W				Other Spotters:		Farid Javadnejad	
Structure:									Dan (
Owner of Structure:			ODOT						Chris	Parrish
Owner's Contact			555 13th St				COA Number:		2015-AHQ-105-	
info:			NE Salem, OR 97301-6867						COA-TS	
			Phone (503) 986-2700				Team 's		(818)-497-8576	
							Emergency Contact			
							Number:			
Airport within 5 nm?			Yes: X No:					Jacob Kropf		
If Yes Which:			J & J airport				Manger Contact info:		(541)-766-6783	
Distance from			3.2 nm					N/A		
Airport:						Air Traffic		UNICOM 123.0		
*							Controller:			
Safe	ty Inv	entory: Ma	rk yes or	no if a	ny of	the following	hazards are poter	ntial fo	or work	k site.
YE	N	Equipmen	nt	YES	N	D 111	1	VEC	N	Environmenta
S	0	Hazards			$ 0 ^P$	Personal Hazards		YES	0	l Hazards
Х		Nearby			x	Twisting/Be	ending/Awkwar		X	Falling Debris
Λ		Vehicular	Traffic			d Positions/	Heavy Lifting			
		Nearby H			x					Confined
X		Equipmen				Working Over water			X	Space
	Operation									Space
		Transport	t/Launc	X		Loose unstable footing				Weather
	X	h of			X			X		Related
		Boat/AT	V/Etc.							
		Boat/Wat	ercraft							Live
	X Operation			X		Slip/Trip/Fall Hazard		X		Stock/Wildlif
		· · · ·				Y 11 / [] 4 1				e
X		ATV Operations		X		Ladders/Elevated Platforms		X		Transients
X		Other			X	Other			X	Other
Λ		Other			Λ	Other			Λ	Other



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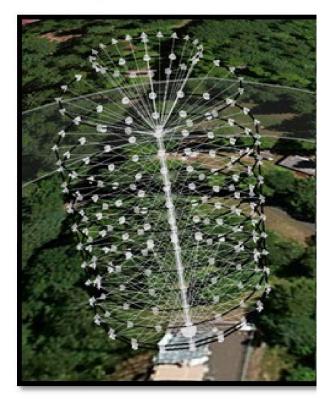
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Courtesy of Chris Glantz, PLS, Oregon Department of Transportation



Related Work: Communication Tower Inspections









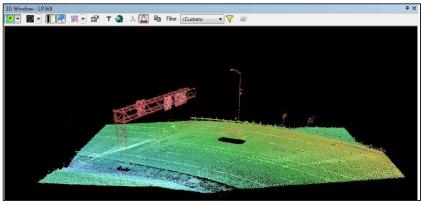


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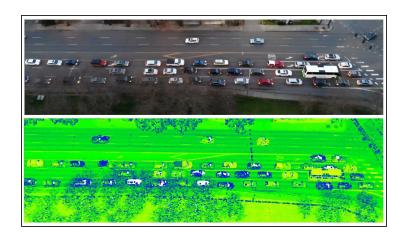


Related Work: UAS Traffic Network Monitoring (PacTrans)











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References

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Questions/Comments/Additional Info:

Contact info:

Christopher.Parrish@oregonstate.edu

204 Owen Hall

Oregon State University

Corvallis, OR 97331



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